Overview

- Software architecture and the need for multiple views
- The build-time software architecture view
- Examples: GCC, Perl, JNI
- The “code robot” architectural style
- Representing build-time views in UML
- Conclusions

Software architecture

- Consists of descriptions of:
  - components, connectors, rationale/constraints, …
- Shows high-level structure
  - Composition and decomposition, horizontal layers and vertical slices
- Reflects major design decisions
  - Rationale for why one approach taken, what impact it has
- Promotes shared mental model among developers and other stakeholders
  - Shows how functional and non-functional requirements are met

The need for multiple views

- Stakeholders have different experiences of what the system “looks like”
  - One size does not fit all.
  - “Separation of concerns”
- Kruchten’s “4+1” model:
  - Logical, development, process, physical “+” scenarios
  - Each view has different elements, different meaning for connectors, etc.
    [Hofmeister et al. proposed similar taxonomy of four views]

The (4+1)++ model

Why the build-time view?

- Many systems do not have very interesting build-time properties …
  - Straightforward, mostly static Makefile-like approach is good enough.
- … but some systems do!
  - They exhibit interesting structural and behavioural properties that are apparent only at system build time.
  - These properties are not well modelled by existing software architecture taxonomies.
Why the build-time view (BTV)?

- Want to document interesting build processes to aid program comprehension
- Targeted at different stakeholders: anyone affected by the build process
  - System “build engineers”
  - Software developers
  - End-users who need to build or customize the application
- Separation of concerns
  - Configuration/build management
- Of particular interest to open source projects

Interesting build-time activities

- Automatic “source” code generation
  - Build-time vs. development-time
    - e.g., GCC vs. JDK
  - Targeted at a large range of CPU/OS platforms
    - Implementation (algorithms) are highly platform dependent.
    - Conditional compilation is not viable.
      - Too complicated or just inelegant

Interesting build-time activities

- Bootstrapping
  - Cross-platform compilation
  - Generation of VMs/interpreters for “special languages”
- Build-time component installation
- Runtime library optimization
  - VIM
- Misc. ad hoc hacks

Build-time view schema

Example 1: GCC bootstrapping

- Same source code is compiled multiple times
  - Each time by a different compiler!
    - Usually, the one built during the previous iteration.
  - Different source modules are included and configured differently for some iterations
- Static analysis (reading) of the Makefiles doesn’t help much in understanding what’s going on.
  - Makefiles are templated, control flow depends on complex interactions with environment.
  - Need to instrument and trace executions of build process, build visual models for comprehension
Example 2:

**GCC build-time code generation**

- In GCC, the common intermediate representation language (i.e., post-parsing) is called the Register Transfer Language (RTL)
  - The RTL is hardware dependent!
  - Therefore, the code that generates and transforms RTL is also hardware dependent.
- RTL related code is generated at build-time
  - Information about the target environment is input as build parameters.

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Example 3:

**PERL building procedures**

- PERL build process exhibits both *bootstrapping* and *build-time code generation*.
  - The PERL build process is so complex that is an open source project in its own right!
- Templates written in XS language are transformed at build-time to generate C files that bridge PERL runtime with Unix runtime libraries.
  - These C files are OS dependent.

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Example 4:

**Use of Java Native Interface (JNI)**

- May want your Java program to make use of an existing C/C++ program for performance or other reasons.
- Need to go through several steps to customize the interaction between the two systems.
  - Similar to Perl XS mechanism, but done for each Java application that requires access to “native” code.
“Code Robot” architecture style

- An architectural style is a recurring abstract pattern of high-level software system structure [Shaw/Garlan]

“Code Robot”

**Problem**: desired behavior of software depends heavily on hardware platform or operating systems.

**Solution**: create customized “source” code at build-time using auto code generator, code templates, other environment-specific customizations.

Examples – some open source systems (e.g., GCC, PERL)

**UML Representation**

- **Static View (UML Component Diagram)**
  - Components:
    - Code written at development phase
    - Code generated at build time
    - Library and executables
    - Environment information
  - Relations:
    - Compile/Link
    - Generate

- **Dynamic View (UML Sequence Diagram)**
  - Model dynamic build procedures
Common reasons for interesting build-time activities

- System building is simply a complex process
- Software aging
  - Older systems gather cruft which is most easily dealt with by build-time hacks
  - Native source language no longer widely supported
  - Ports to new environments dealt with at build-time
- Complex environmental dependencies which must be resolved by querying the target platform
  - Especially true for open source software
  - Common for compiler-like applications

Conclusions

- Build-time view captures interesting structural and behavioral properties of some classes of software.
- Can aid program understanding by instrumenting build tools and creating explicit build-time models
  - UML component and sequence diagrams can be used
- “Code robot” architectural style
  - Common in systems with interesting BTVs
- Future work:
  - More case studies and exploration of problem space
    - Discover recurring patterns of build-time activities
  - Develop tools to (semi) auto-extract and create build-time views